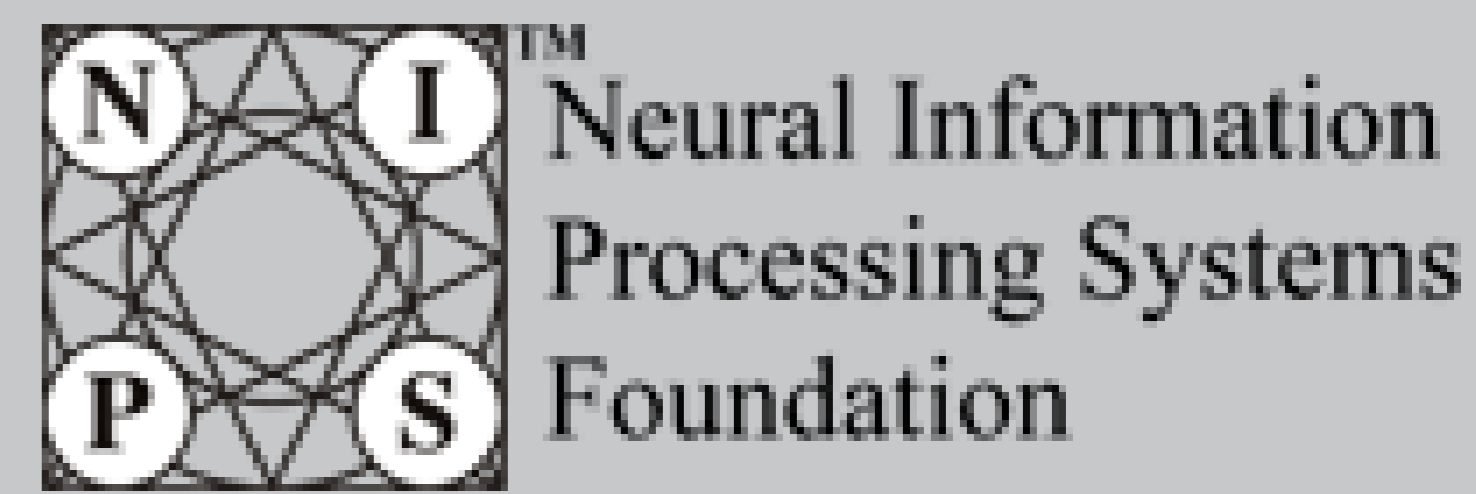


# Expectation Propagation for the Estimation of Conditional Bivariate Copulas

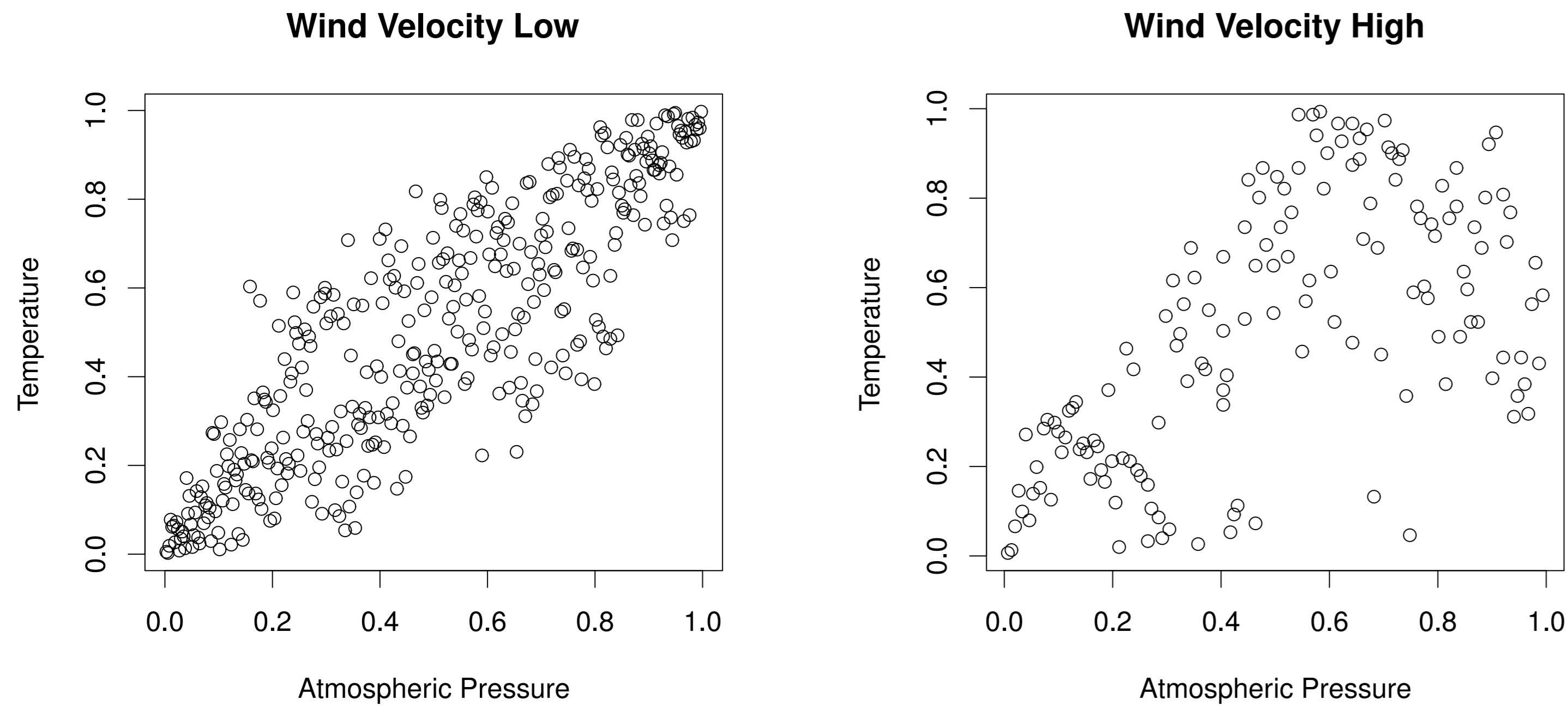
José Miguel Hernández-Lobato(1), David López-Paz(2) and Zoubin Ghahramani(1)

(1) - Department of Engineering, Cambridge University  
(2) - Max Planck Institute for Intelligent Systems, Tübingen, Germany



## Copulas and Covariates

A bivariate copula  $\mathbf{C}$  may depend on a **covariate** denoted by  $\mathbf{Z}$ .



## Conditional Copulas

We can adjust for the effect of  $\mathbf{Z}$  by modelling the conditional copula.

**Conditional Copula:** [Patton 2006]

Let  $F_{X|Z}$  and  $F_{Y|Z}$  be the conditional marginals of  $X$  and  $Y$  given  $Z$ . The conditional copula  $\mathbf{C}_Z$  for  $X$  and  $Y$  is the distribution of  $F_{X|Z}(X|Z)$  and  $F_{Y|Z}(Y|Z)$ .

**Extension of Sklar's Theorem:** [Patton 2006]

Let  $F_{X|Z}$  and  $F_{Y|Z}$  be the conditional marginals of  $X$  and  $Y$  given  $Z$ . Let  $F_Z$  be the conditional distribution with continuous marginals  $F_{X|Z}$  and  $F_{Y|Z}$ . Then, there is a unique conditional copula  $\mathbf{C}_Z$  such that  $F_Z(\mathbf{x}, \mathbf{y}|z) = \mathbf{C}_Z[F_{X|Z}(\mathbf{x}|z), F_{Y|Z}(\mathbf{y}|z)|z]$ .

The estimation of  $F_Z$  from a sample  $\{X_i, Y_i, Z_i\}_{i=1}^n$  can then be done by

1. Estimating  $F_{X|Z}$  and  $F_{Y|Z}$  using our favorite method.
2.  $\{X_i, Y_i\}_{i=1}^n$  to  $[0, 1]^2$  using the estimates for  $F_{X|Z}$  and  $F_{Y|Z}$ .
3. Estimating  $\mathbf{C}_Z$  using the data from the step 2. **We need a model for  $\mathbf{C}_Z$ .**

## A Semi-parametric Model for Conditional Copulas

We describe  $\mathbf{C}_Z$  using a **parametric model** specified in terms of Kendall's tau.

**Kendall's tau:** [Joe 1997]

Let  $(U_1, V_1)$  and  $(U_2, V_2)$  be two independent samples from a bivariate copula  $\mathbf{C}$ . Kendall's tau is  $\tau = \mathcal{P}[(U_1 - U_2)(V_1 - V_2) > 0] - \mathcal{P}[(U_1 - U_2)(V_1 - V_2) < 0]$ .

- \*  $\tau = 0 \leftrightarrow U$  and  $V$  are independent.
- \*  $\tau = 1 \leftrightarrow U$  and  $V$  have perfect positive dependence.
- \*  $\tau = -1 \leftrightarrow U$  and  $V$  have perfect negative dependence.

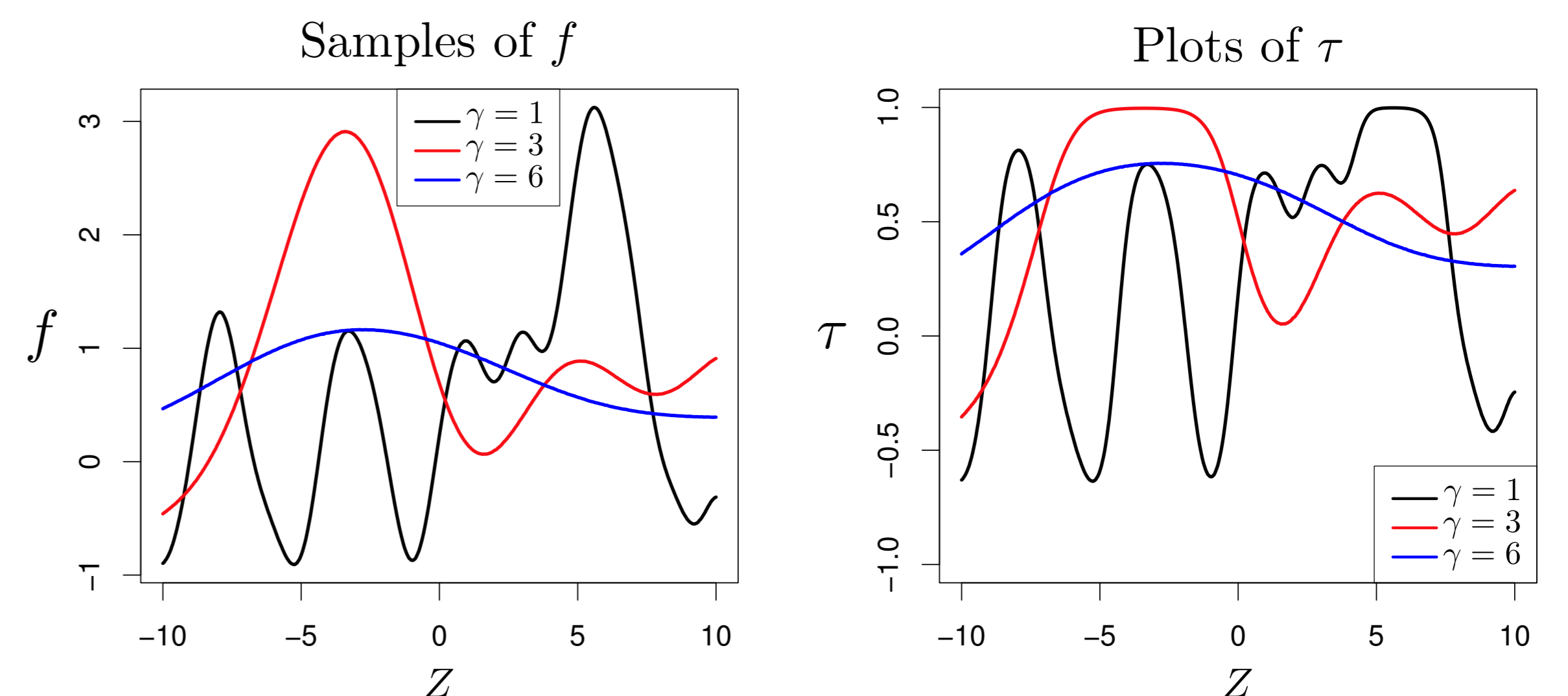
Most parametric bivariate copulas are **fully determined given  $\tau$** .

For example, in the Gaussian copula,  $\rho = \sin(\tau\pi/2)$ .

The dependence of  $\mathbf{C}_Z$  on  $\mathbf{Z}$  is captured by the relationship  $\tau = \sigma[f(\mathbf{Z})]$ , where  $f$  is an arbitrary non-linear function and  $\sigma(x) = 2\Phi(x) - 1$  is a sigmoid function.

## Bayesian Inference

We assume that  $f$  follows *a priori* a **Gaussian process** with zero mean and covariance function  $k[f(\mathbf{Z}_i), f(\mathbf{Z}_j)] = \exp\{-0.5\gamma^{-2}(\mathbf{Z}_i - \mathbf{Z}_j)^2\}$ .



## Expectation Propagation [Minka 2001]

EP approximates the posterior  $\mathcal{P}(f|\mathcal{D}_{UV}, \mathcal{D}_Z)$  by a simpler distribution  $\mathcal{Q}(f) = \mathcal{N}(f|\mathbf{m}, \mathbf{V})$ , where

$$\mathcal{P}(f|\mathcal{D}_{UV}, \mathcal{D}_Z) \propto \mathcal{P}(U_1, V_1|\tau = \sigma[f_1]) \cdots \mathcal{P}(U_n, V_n|\tau = \sigma[f_n]) \mathcal{N}(f|\mathbf{0}, \mathbf{K})$$

$$\mathcal{Q}(f) \propto \underbrace{k_1 \mathcal{N}(f_1|\hat{m}_1, \hat{v}_1)}_{\hat{q}_1(f_1)} \cdots \underbrace{k_n \mathcal{N}(f_n|\hat{m}_n, \hat{v}_n)}_{\hat{q}_n(f_n)} \mathcal{N}(f|\mathbf{0}, \mathbf{K})$$

EP tunes  $\hat{m}_i$  and  $\hat{v}_i$  by minimizing  $\text{KL}[q_i(f_i)\mathcal{Q}(f)[\hat{q}_i(f_i)]^{-1}||\mathcal{Q}(f)]$ ,  $i = 1, \dots, n$ . Similar to EP for Gaussian process classification [Rasmussen and Williams 2006].

We fix  $\gamma$  by maximizing the EP approx. of  $\mathcal{P}(\mathcal{D}_{UV}|\mathcal{D}_Z)$ . The total cost is  $\mathcal{O}(n^3)$ .

## Experiments with Synthetic and Real-world Data

We choose a **Gaussian copula** for the likelihood function  $\mathcal{P}(u, v|\tau = \sigma[f(z)])$ .

**Synthetic Data:**

1000 points.  $\mathbf{Z}$  sampled uniformly from  $[0, \pi]$ .  $\mathbf{U}$  and  $\mathbf{V}$  sampled from a Gaussian copula with  $\tau = 0.5 \cos(3z)$ .

**Meteorological Data:**

522 points. Atmospheric pressure ( $\mathbf{X}$ ), Temperature ( $\mathbf{Y}$ ) and Wind Velocity ( $\mathbf{Z}$ ). Conditional marginals  $F_{X|Z}$  and  $F_{Y|Z}$  estimated using kernels [Hall et al. 2004]. These estimates are used to map  $\mathbf{X}$  and  $\mathbf{Y}$  into  $\mathbf{U}$  and  $\mathbf{V}$ .

**Experimental Protocol:**

Training sets with 100 observations.

40 repetitions. Test log-likelihood (TLL) used as a measure of performance.

**Benchmark Methods:**

- \* **GC:** Parametric Gaussian copula with no dependence on  $\mathbf{Z}$ .
- \* **MLL:** Non-parametric maximum local likelihood estimator of  $f$  [Acar et al. 2011].

## Results

**EP-CC:** The EP method for the estimation of conditional copulas.

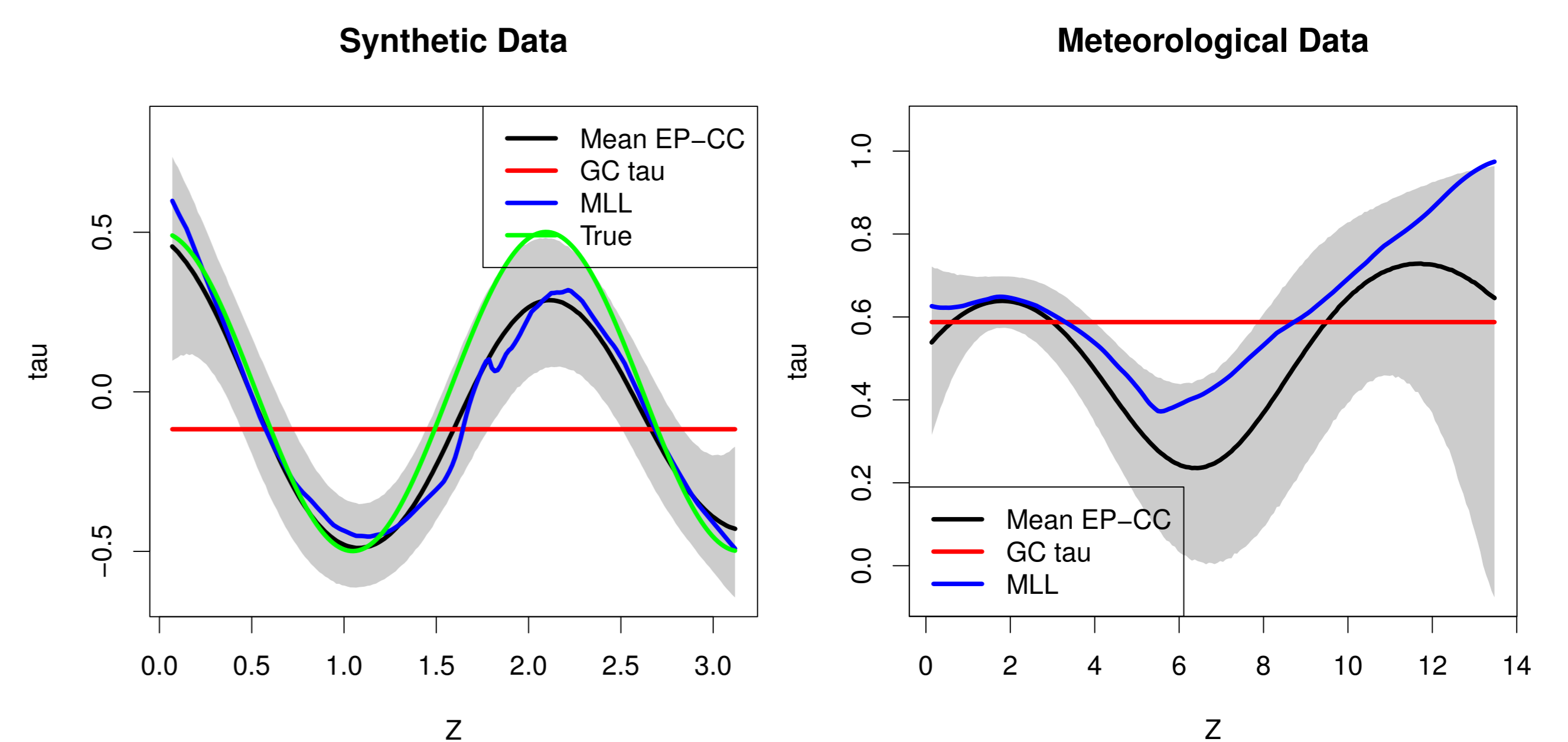
Dataset	Method	Avg. TLL	p-value <sup>1</sup>
Synthetic	EP-CC	0.13±0.021	-
	MLL	0.06±0.150	0.002
	GC	-0.01±0.017	< 2.2 · 10 <sup>-16</sup>
Meteorological	EP-CC	0.49±0.019	-
	MLL	0.42±0.479	0.35
	GC	0.47±0.029	7.03 · 10 <sup>-5</sup>

1: p-value of a paired Student's  $t$  test between EP-CC and the other methods.

EP-CC is **more robust** than MLL.

The meteorological data have a copula that **depends** on the wind velocity.

## Plots of $f$ for each Dataset (200 training points)



## Conclusions

- ▶ We have proposed a **semi-parametric** model for conditional copulas. The model employs a **Gaussian process** prior.
- ▶ **Expectation propagation** is used for efficient Bayesian inference.
- ▶ The performance of this method (EP-CC) has been illustrated in experiments with **synthetic** and **meteorological** data.
- ▶ In these experiments, EP-CC is **more robust** and can perform better than other approaches that maximize the local likelihood.

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